

NAG C Library Function Document

nag_zhbtrd (f08hsc)

1 Purpose

nag_zhbtrd (f08hsc) reduces a complex Hermitian band matrix to tridiagonal form.

2 Specification

```
void nag_zhbtrd (Nag_OrderType order, Nag_VectType vect, Nag_UploType uplo,
                Integer n, Integer kd, Complex ab[], Integer pdab, double d[], double e[],
                Complex q[], Integer pdq, NagError *fail)
```

3 Description

The Hermitian band matrix A is reduced to real symmetric tridiagonal form T by a unitary similarity transformation: $T = Q^H A Q$. The unitary matrix Q is determined as a product of Givens rotation matrices, and may be formed explicitly by the function if required.

The function uses a vectorisable form of the reduction, due to Kaufman (1984).

4 References

Kaufman L (1984) Banded eigenvalue solvers on vector machines *ACM Trans. Math. Software* **10** 73–86

Parlett B N (1998) *The Symmetric Eigenvalue Problem* SIAM, Philadelphia

5 Parameters

1: **order** – Nag_OrderType *Input*

On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order = Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

Constraint: **order = Nag_RowMajor** or **Nag_ColMajor**.

2: **vect** – Nag_VectType *Input*

On entry: indicates whether Q is to be returned as follows:

- if **vect = Nag_FormQ**, Q is returned (and the array **q** must contain a matrix on entry);
- if **vect = Nag_UpdateQ**, Q is updated (and the array **q** must contain a matrix on entry);
- if **vect = Nag_DoNotForm**, Q is not required.

Constraint: **vect = Nag_FormQ**, **Nag_UpdateQ** or **Nag_DoNotForm**.

3: **uplo** – Nag_UploType *Input*

On entry: indicates whether the upper or lower triangular part of A is stored as follows:

- if **uplo = Nag_Upper**, then the upper triangular part of A is stored;
- if **uplo = Nag_Lower**, then the lower triangular part of A is stored.

Constraint: **uplo = Nag_Upper** or **Nag_Lower**.

- 4: **n** – Integer *Input*
On entry: n , the order of the matrix A .
Constraint: $n \geq 0$.
- 5: **kd** – Integer *Input*
On entry: k , the number of super-diagonals of the matrix A if **uplo** = **Nag_Upper**, or the number of sub-diagonals if **uplo** = **Nag_Lower**.
Constraint: $kd \geq 0$.
- 6: **ab**[*dim*] – Complex *Input/Output*
Note: the dimension, *dim*, of the array **ab** must be at least $\max(1, \mathbf{pdab} \times \mathbf{n})$.
On entry: the n by n Hermitian band matrix A with k sub or super-diagonals. This is stored as a notional two-dimensional array with row elements or column elements stored contiguously. Just the upper or lower triangular part of the array is held depending on the value of **uplo**. The storage of elements a_{ij} depends on the **order** and **uplo** parameters as follows:
 if **order** = **Nag_ColMajor** and **uplo** = **Nag_Upper**,
 a_{ij} is stored in **ab**[$k + i - j + (j - 1) \times \mathbf{pdab}$], for $i = 1, \dots, n$ and
 $j = i, \dots, \min(n, i + k)$;
 if **order** = **Nag_ColMajor** and **uplo** = **Nag_Lower**,
 a_{ij} is stored in **ab**[$i - j + (j - 1) \times \mathbf{pdab}$], for $i = 1, \dots, n$ and
 $j = \max(1, i - k), \dots, i$;
 if **order** = **Nag_RowMajor** and **uplo** = **Nag_Upper**,
 a_{ij} is stored in **ab**[$j - i + (i - 1) \times \mathbf{pdab}$], for $i = 1, \dots, n$ and
 $j = i, \dots, \min(n, i + k)$;
 if **order** = **Nag_RowMajor** and **uplo** = **Nag_Lower**,
 a_{ij} is stored in **ab**[$k + j - i + (i - 1) \times \mathbf{pdab}$], for $i = 1, \dots, n$ and
 $j = \max(1, i - k), \dots, i$.
On exit: A is overwritten.
- 7: **pdab** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix A in the array **ab**.
Constraint: $\mathbf{pdab} \geq \max(1, \mathbf{kd} + 1)$.
- 8: **d**[*dim*] – double *Output*
Note: the dimension, *dim*, of the array **d** must be at least $\max(1, \mathbf{n})$.
On exit: the diagonal elements of the tridiagonal matrix T .
- 9: **e**[*dim*] – double *Output*
Note: the dimension, *dim*, of the array **e** must be at least $\max(1, \mathbf{n} - 1)$.
On exit: the off-diagonal elements of the tridiagonal matrix T .
- 10: **q**[*dim*] – Complex *Input/Output*
Note: the dimension, *dim*, of the array **q** must be at least
 $\max(1, \mathbf{pdq} \times \mathbf{n})$ when **vect** = **Nag_FormQ** or **Nag_UpdateQ**;
 1 when **vect** = **Nag_DoNotForm**.
 If **order** = **Nag_ColMajor**, the (i, j) th element of the matrix Q is stored in **q**[($j - 1$) \times **pdq** + $i - 1$]
 and if **order** = **Nag_RowMajor**, the (i, j) th element of the matrix Q is stored in
q[($i - 1$) \times **pdq** + $j - 1$].

On entry: if **vect** = **Nag_UpdateQ**, **q** must contain the matrix formed in a previous stage of the reduction (for example, the reduction of a banded Hermitian-definite generalized eigenproblem); otherwise **q** need not be set.

On exit: if **vect** = **Nag_FormQ** or **Nag_UpdateQ**, the n by n matrix Q .

q is not referenced if **vect** = **Nag_DoNotForm**.

11: **pdq** – Integer

Input

On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **q**.

Constraints:

if **vect** = **Nag_FormQ** or **Nag_UpdateQ**, $\text{pdq} \geq \max(1, \mathbf{n})$;
if **vect** = **Nag_DoNotForm**, $\text{pdq} \geq 1$.

12: **fail** – NagError *

Output

The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, **n** = $\langle \text{value} \rangle$.

Constraint: $\mathbf{n} \geq 0$.

On entry, **kd** = $\langle \text{value} \rangle$.

Constraint: $\mathbf{kd} \geq 0$.

On entry, **pdab** = $\langle \text{value} \rangle$.

Constraint: $\mathbf{pdab} > 0$.

On entry, **pdq** = $\langle \text{value} \rangle$.

Constraint: $\mathbf{pdq} > 0$.

NE_INT_2

On entry, **pdab** = $\langle \text{value} \rangle$, **kd** = $\langle \text{value} \rangle$.

Constraint: $\mathbf{pdab} \geq \max(1, \mathbf{kd} + 1)$.

NE_ENUM_INT_2

On entry, **vect** = $\langle \text{value} \rangle$, **n** = $\langle \text{value} \rangle$, **pdq** = $\langle \text{value} \rangle$.

Constraint: if **vect** = **Nag_FormQ** or **Nag_UpdateQ**, $\text{pdq} \geq \max(1, \mathbf{n})$;
if **vect** = **Nag_DoNotForm**, $\text{pdq} \geq 1$.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter $\langle \text{value} \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

The computed tridiagonal matrix T is exactly similar to a nearby matrix $A + E$, where

$$\|E\|_2 \leq c(n)\epsilon\|A\|_2,$$

$c(n)$ is a modestly increasing function of n , and ϵ is the *machine precision*.

The elements of T themselves may be sensitive to small perturbations in A or to rounding errors in the computation, but this does not affect the stability of the eigenvalues and eigenvectors.

The computed matrix Q differs from an exactly unitary matrix by a matrix E such that

$$\|E\|_2 = O(\epsilon),$$

where ϵ is the *machine precision*.

8 Further Comments

The total number of real floating-point operations is approximately $20n^2k$ if **vect** = **Nag_DoNotForm** with $10n^3(k-1)/k$ additional operations if **vect** = **Nag_FormQ**.

The real analogue of this function is nag_dsbrtd (f08hec).

9 Example

To compute all the eigenvalues and eigenvectors of the matrix A , where

$$A = \begin{pmatrix} -3.13 + 0.00i & 1.94 - 2.10i & -3.40 + 0.25i & 0.00 + 0.00i \\ 1.94 + 2.10i & -1.91 + 0.00i & -0.82 - 0.89i & -0.67 + 0.34i \\ -3.40 - 0.25i & -0.82 + 0.89i & -2.87 + 0.00i & -2.10 - 0.16i \\ 0.00 + 0.00i & -0.67 - 0.34i & -2.10 + 0.16i & 0.50 + 0.00i \end{pmatrix}.$$

Here A is Hermitian and is treated as a band matrix. The program first calls nag_zhbtrd (f08hsc) to reduce A to tridiagonal form T , and to form the unitary matrix Q ; the results are then passed to nag_zsteqr (f08jsc) which computes the eigenvalues and eigenvectors of A .

9.1 Program Text

```

/* nag_zhbtrd (f08hsc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf08.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer i, j, k, kd, n, pdab, pdz, d_len, e_len;
    Integer exit_status=0;
    NagError fail;
    Nag_UploType uplo;
    Nag_OrderType order;
    /* Arrays */
    char uplo_char[2];
    Complex *ab=0, *z=0;
    double *d=0, *e=0;

#ifdef NAG_COLUMN_MAJOR
#define AB_UPPER(I,J) ab[(J-1)*pdab + k + I - J - 1]

```

```

#define AB_LOWER(I,J) ab[(J-1)*pdab + I - J]
    order = Nag_ColMajor;
#else
#define AB_UPPER(I,J) ab[(I-1)*pdab + J - I]
#define AB_LOWER(I,J) ab[(I-1)*pdab + k + J - I - 1]
    order = Nag_RowMajor;
#endif

INIT_FAIL(fail);
Vprintf("f08hsc Example Program Results\n\n");

/* Skip heading in data file */
Vscanf("%*[\n] ");
Vscanf("%ld%ld%*[\n] ", &n, &kd);
pdab = kd + 1;
pdz = n;
d_len = n;
e_len = n-1;

/* Allocate memory */
if ( !(ab = NAG_ALLOC(pdab * n, Complex)) ||
      !(d = NAG_ALLOC(d_len, double)) ||
      !(e = NAG_ALLOC(e_len, double)) ||
      !(z = NAG_ALLOC(pdz * n, Complex)) )
{
    Vprintf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

/* Read A from data file */
Vscanf(" ' %ls '%*[\n] ", uplo_char);
if (*(unsigned char *)uplo_char == 'L')
    uplo = Nag_Lower;
else if (*(unsigned char *)uplo_char == 'U')
    uplo = Nag_Upper;
else
{
    Vprintf("Unrecognised character for Nag_UploType type\n");
    exit_status = -1;
    goto END;
}
k = kd + 1;
if (uplo == Nag_Upper)
{
    for (i = 1; i <= n; ++i)
    {
        for (j = i; j <= MIN(i+kd,n); ++j)
            Vscanf(" ( %lf , %lf )", &AB_UPPER(i,j).re, &AB_UPPER(i,j).im);
    }
    Vscanf("%*[\n] ");
}
else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = MAX(1,i-kd); j <= i; ++j)
            Vscanf(" ( %lf , %lf )", &AB_LOWER(i,j).re, &AB_LOWER(i,j).im);
    }
    Vscanf("%*[\n] ");
}

/* Reduce A to tridiagonal form */
f08hsc(order, Nag_FormQ, uplo, n, kd, ab, pdab, d, e,
        z, pdz, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f08hsc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

```

```

/* Calculate all the eigenvalues and eigenvectors of A */
f08jsc(order, Nag_UpdateZ, n, d, e, z, pdz, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f08jsc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Print eigenvalues and eigenvectors */
Vprintf(" Eigenvalues\n");
for (i = 1; i <= n; ++i)
    Vprintf("%8.4f%s", d[i-1], i%8==0 ? "\n": " ");
Vprintf("\n\n");
x04dbc(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, n,
        z, pdz, Nag_BracketForm, "%7.4f", "Eigenvectors",
        Nag_IntegerLabels, 0, Nag_IntegerLabels, 0, 80,
        0, 0, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from x04dbc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
END:
if (ab) NAG_FREE(ab);
if (d) NAG_FREE(d);
if (e) NAG_FREE(e);
if (z) NAG_FREE(z);

return exit_status;
}

```

9.2 Program Data

f08hsc Example Program Data

```

4 2                                     :Values of N and KD
'L'                                     :Value of UPLO
(-3.13, 0.00)
( 1.94, 2.10) (-1.91, 0.00)
(-3.40,-0.25) (-0.82, 0.89) (-2.87, 0.00)
                (-0.67,-0.34) (-2.10, 0.16) ( 0.50, 0.00) :End of matrix A

```

9.3 Program Results

f08hsc Example Program Results

```

Eigenvalues
-7.0042          -4.0038          0.5968          3.0012

Eigenvectors
                1                2                3                4
1 ( 0.7293, 0.0000) (-0.2128, 0.1511) (-0.3354,-0.1604) (-0.5114,-0.0163)
2 (-0.1654,-0.2046) ( 0.7316, 0.0000) (-0.2804,-0.3413) (-0.2374,-0.3796)
3 ( 0.6081, 0.0301) ( 0.3910,-0.3843) (-0.0144, 0.1532) ( 0.5523, 0.0000)
4 ( 0.1653,-0.0303) ( 0.2775,-0.1378) ( 0.8019, 0.0000) (-0.4517, 0.1693)

```
